INSTRUCTION MANUAL

UV-A radiometer UV-B radiometer

MS-10S MS-11S



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2. Important User Information

Thank you for using EKO Products.

Reading this manual is recommended prior to installation and operation of the product. Keep this manual in a safe and handy place for whenever it is needed. For any questions, please contact us at below:

2-1. Contact Information

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2-2. Warranty and Liability

For warranty terms and conditions, please contact EKO Instruments or your distributer for further details.

EKO guarantees that the product delivered to customer has been tested to ensure the instrument meets its published specifications. The warranty included in the conditions of delivery is valid only if the product has been installed and used according to the instructions provided in this operating manual.

In case any manufacturing defect[s] occurs, the defected part[s] will be repaired or replaced under warranty; however, the warranty will not be applicable if:

- > Any modification or repair has been done by other than EKO service personnel.
- The damage or defect is caused by disrespecting the specifications mentioned on the product brochure or instruction manual.
- Spirit level
- Discoloration of the UV radiometer body, sun screen, and cable within a range that does not affect the function and performance.

2-3. About Instruction Manual

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This manual was issued:May 23, 2022Version Number:1

2-4. Environment

1. WEEE Directive 2002/96/EC [Waste Electrical and Electronic Equipment]

In August of 2005, the European Union [EU] implemented the EU WEEE Directive 2002/96/EC and later the WEEE Recast Directive 2012/19/EU requiring Producers of electronic and electrical equipment [EEE] to manage and finance the collection, reuse, recycling and to appropriately treat WEEE that the Producer places on the EU market after August 13, 2005. The goal of this directive is to minimize the volume of electrical and electronic waste disposal and to encourage re-use and recycling at the end of life.

EKO products are subject to the WEEE Directive 2002/96/EC. EKO Instruments has labeled its branded electronic products with the WEEE Symbol [figure Trash bin] to alert our customers that products bearing this label should not be disposed of in a landfill or with municipal or household waste in the EU.

If you have purchased EKO Instruments branded electrical or electronic products in the EU and are intending to discard these products at the end of their useful life, please do not dispose of them with your other household or municipal waste. Disposing of this product correctly will help save valuable resources and prevent any potential negative effects on human health and the environment, which could otherwise arise from inappropriate waste handling.

2. RoHS Directive 2002/95/EC

EKO Instruments has completed a comprehensive evaluation of its product range to ensure compliance with RoHS Directive 2002/95/EC regarding maximum concentration values for substances. As a result all products are manufactured using raw materials that do not contain any of the restricted substances referred to in the RoHS Directive 2002/95/EC at concentration levels in excess of those permitted under the RoHS Directive 2002/95/EC, or up to levels allowed in excess of these concentrations by the Annex to the RoHS Directive 2002/95/EC.

2-5. CE 宣言書



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DECLARATION OF CONFORMITY

We: EKO INSTRUMENTS CO., LTD 1-21-8 Hatagaya Shibuya-ku, Tokyo 151-0072 JAPAN

Declare under our sole responsibility that the product:

Product Name:UV RadiometerModel No.:MS-10S, MS-11S

To which this declaration relates is in conformity with the following harmonized standards of other normative documents:

Harmonized standards:

EN 61326-1:2013 (Emission) CISPR11 Class A EN 61326-1:2013 (Immunity) EN 61000-4-2 EN 61000-4-3 EN 61000-4-4 EN 61000-4-5 EN 61000-4-6

Following the provisions of the directive:

EMC-directive : 2014/30/EU LowVoltage-directive: 2014/35/EU

Date:	December 14 , 2021
Position of Authorized Signatory:	General Manager of R & D Center
Name of Authorized Signatory:	Kiyotaka Uchida
Signature of Authorized Signatory:	kuchid

3. Safety Information

EKO Products are designed and manufactured with consideration for safety; however, please make sure to read and understand this instruction manual thoroughly to be able to operate the instrument safely in the correct manner.



Attention to user; pay attention to the instructions given on the instruction manual with this sign.



High voltage is used; pay special attention to instructions given on this instruction manual with this sign to prevent electric leakage and/or electric shocks.



3-1. General Warnings

1. Setup

- The installation base or mast should have enough load capacity for the instrument to be mounted. Fix the UV radiometer securely to the base or mast with bolts and nuts; otherwise, the instrument may drop due to a gale or an earthquake, which may lead to unexpected accidents.
- Make sure to install the instrument and cables in a suitable location, and avoid submersion in water.
- When connecting this product to a measuring instrument for measurement, connect the shield wire of the output cable to signal ground (SG). Noises may be included in the measurement data.
- Although this product is tested to meet EMC Directive compliance requirements, it may not fully satisfy its primary specification/performance when using this product near following locations where strong electromagnetic wave is generated. Please pay attention to the installation environment.

Outdoor: High voltage power line, power receiver/distribution facility, etc.

Indoor: Large-size chiller, large electric motors, microwave, etc.

- Do not use this product in the environment where corrosive gas, such as ammonia and sulfurous acid gas, are generated. It may cause malfunction.
- Do not install in the area that cause salt damages. It may cause malfunction by paint peeling off or corrosion. When installing in the area with risk of salt damages, make sure to take following measures:
 - 1. Wrap the connector with self-fusing tape
 - 2. Change the fixing screw to bolt screw made of aluminum
 - 3. Run the cables in a plastic or metal pipe treated with salt-resistant paint such as molten zinc plating
 - 4. Periodically clean.
- Do not use this instrument in the vacuum environment.
- For proper grounding use the original cable provided.
- If the cable and sensor is in risk for getting damaged by birds and small animals, protect the cable and the sensor by using:
 - 1. Reflective tape
 - 2. Repellent
 - 3. Cable duct
 - 4. Installing bird-spike

When using the configurable 0 to 1V output from MS-10S/11S, please use a precision resistor 100Ω. The settings can be changed with the 485 / USB conversion cable and dedicated software.

2. Handling

- Be careful when handling instruments with glass domes. Strong impact to this part may damage the glass and may cause injuries by broken glass parts.
- When carrying any model with the sun screen attached, always hold the instrument from the bottom. Holding only the sun screen part may lead to dropping the sensor as it comes off from the sun screen.

3. Signal Cable

- Make sure to ground the signal cable. When grounding is insufficient, it may cause not only measurement error due to noise, but also cause electric shock and leakage accidents.
- Check the voltage and types of specified power supply before connecting this instrument. When improper power supply is connected, it may cause malfunction and/or accident.
- Use this instrument with 0.5A fuse connected to the power supply line in series. Without connecting the fuse, it has risks of generating heat and fire due to large-current flowing by the power supply when internal damage of the electronics occurs.

4. About RS-485 Modbus connection

- > This product supports communication through the RS-485 Modbus RTU.
- > It is recommended to use the optional EKO converter cable when connecting MS-10S/11S to a PC.
- > Depending on the USB-RS485 converter type, an additional termination resistor (120 Ω) and/or pullup/pull-down resistor (680 Ω) is required for proper communication.
- When connecting to a RS-485 (Modbus) master peripheral device, an additional termination resistor (120Ω) and/or pull-up/pull-down resistor (680Ω) is required for proper communication.

4. Introduction

The MS-10S is an UV radiometer that continuously measures irradiance in the UV-A region (315-400nm), and the MS-11S is in the UV-B region (280-315nm).

The ozone layer absorbs harmful ultraviolet radiation from the sun and plays an important role in protecting human beings and other living things. Recently, it has been confirmed that the ozone layer is decreasing, and this has become a major problem.

UV radiation is usually divided into three wavelength ranges: UV-A (315-400nm), UV-B (280-315nm), and UV-C (below 280nm). Of these, UV-A light is only slightly absorbed by the ozone layer, so it is not affected by changes in the ozone layer. UV-B light fluctuates greatly depending on the amount of ozone and is harmful to living things, so it is generally referred to as "harmful ultraviolet light.

4-1. Main features

- 1. Capable of measuring ultraviolet radiation in the UV-A and UV-B spectral region
- 2. Rainproof structure for constant measurement
- 3. Multioutput (Modbus 485 RTU, SDI-12, 4-20mA, 0-10mA/0-1V with external 100 Ω precision shunt resistor.)
- 4. Wide voltage supply input range (5VDC or 8-30VDC)
- 5. With built-in tilt/roll sensor

4-2. Package Contents

Check the package contents first; if any missing parts or any damage is noticed, please contact EKO immediately.

Table 4-1. Package Contents

Contents	MS-10S/11S
UV-radiometer	1
Output Cable	✓ (1)
Sun screen	1
Instruction Manual	Not included in the package. (Please download the manual from the EKO website.)
Setting Report	✓ (2)
Temperature dependency report	<i>✓</i>
Cosine response report	✓
Calibration certificate	1
Fixing Bolts	[M5] x2 [Bolt Length: 75mm]
Washers	[M5] x4
Nuts	[M5] x2

(1) In case of MS-10S/11S, standard length is 10m for signal/power cable. For different length of cable [e.g. to meet your application needs] please contact EKO or your local distributor.

(2) Details about the setting report, see appendix A-6.

5. Getting Started

5-1. Parts Name and Descriptions

Each part name and its main function is described below.



*Signal converter is built-in for MS-10S/11S. Figure 5-1. UV radiometer Parts Name

1. Glass Dome, Quartz Diffuser

A glass dome creates a sealed environment for the detector and protects it against dirt and rain. The dome of the EKO UV radiometers is only transparent for radiation emitted by the sun. The combination of the glass dome and the Quartz diffuser give a 180 degrees field of view and good cosine response.

2. Detector

The heart of the product is the detector (UV-A or UV-B dedicated photodiode), which generates a voltage proportional to the irradiance of UV-A or UV-B spectral region. The detector determines the main characteristics of the UV radiometer (response time, temperature characteristics, non-linearity, sensitivity constant, etc.).

3. Sun screen, Body

MS-10S/11S have a sun screen to prevent any excessive body temperature increase generated by direct sun light. Weather resistant metals are used to reduce the effects and degradation caused by heat radiation, rain, and windblown dusts.

4. Spirit level

The integrated spirit level is used for setup and maintaining the sensor in a horizontally levelled position.

* Depending on the operating environment, bubbles may come out of the level gauge, liquid may be missing, the reference circles may fade out, or cracks may occur.

5. Drying agent

Enclosed drying agents inside the sensor body keep the sensor inside dry, prevents condensation of humidity inside of the glass dome.

6. Cable and Cable Connector

MS-10S/11S are shipped with a 10 meter long output cable as standard length*.

Durable materials are used for the cable and connector, and pin terminals are attached at the end of the cable for easy connection with a data logger terminal block.

* If longer cables, round terminals or fork terminals are required, please contact EKO Instruments or your distributor. Also see [7. Specification, 7-4. Accessories List] for optional items.

The connector should be protected by the self-fusing tape when the UV radiometers are used in the areas with the risk of the salt damage.

5-2. Setup

In order to obtain high quality measurements from UV radiometers, several criteria with respect to setup and mounting of the instruments have to be considered. Also see the Quick Start Guide for comprehensive setup instruction details

The ideal mounting position for a UV radiometer is a location which has a full hemispheric field-of-view without any obstructions [such as buildings, trees, and mountains]; however, it might be difficult to find such locations. Therefore in practice, it is ideal to install in a position which is free from obstructions at 5° above horizon.

The setup location should be easily accessible for periodic maintenance [glass dome cleaning], and avoid surrounding towers, poles, walls or billboards with bright colors that can reflect solar radiation onto the UV radiometer.

A strong physical impact to the UV radiometer can lead to product damage and/or may cause changes to the sensitivity.

1. Installing at Horizontal or Tilted Position

1) Check the installation base where the UV radiometer has to be mounted and make sure it has two fixing holes with the appropriate pitch. The pitch sizes of the fixing holes are as follows [in mm]:

	MS-10S/11S
Fixing Hole Pitch	65 mm
Fixing Bolt Size	M5 x 75 mm

Table 5-2. Fixing Hole Pitch and Bolt Size for UV radiometers

2) Remove a sun screen

The sun screen can be removed by loosening the knurling screw and sliding it towards the spirit level direction. *When carrying MS-10S/11S with a sun screen attached, always hold the instrument from the bottom. Holding only the sun screen may lead to dropping the sensor as it comes off from the sun screen.

3) There are two ways to setup the UV radiometer (Horizontal or inclined).

Installing at horizontal Position

Setup the UV radiometer with the signal cable connector facing the nearest Earth's pole. In the Northern hemisphere, the connector should be orientated North, in the Southern hemisphere, the connector should be orientated South. Adjust the UV radiometer in a horizontal position by using the 2 levelling screws observing the air bubble in the spirit level while manipulating the levelling screws. The instrument is levelled horizontally if the air bubble is in the centre ring. The sensitivity of the bubble vial is (0.1° / mm). If the UV radiometer is not levelled properly, the UV radiometer readings are affected by cosine and azimuth errors. Periodically check the spirit level and adjust the UV radiometer's position if necessary.

Installing at an inclined angle

After the MS-10S/11S is adjusted to horizontal position in levelled surface, install it on tilted a tilted mount.

In the case of MS-10S/11S, it is possible to acquire tilt information obtained from the built-in tilt position sensor through Modbus RTU. The sensor position can be measured in two different planes (X,Y).



<Tilt (X axis)> <Roll (Y axis)> (180° to 0) and (0 to -180°) (180° to 0) and (0 to -180°)

Figure 5.2A Tilt angle (-180 to 0°) and (0 to 180°) Roll angle (-180 to 0°) and (0 to 180°)

The tilt and roll angles are relative to the calibrated X and Y axis of the sensor and surface mounting plane X' and Y'. When the sensor is positioned in the same plane X = X' and Y = Y', the measured tilt and roll angles (X and Y) correspond to plane of installation X' and Y'.

The UV radiometer connector is an important reference for setup and corresponds to the Xaxis reference plane.



<u>For setup at horizontal plane</u>: Setup the UV radiometer with the signal cable connector facing the nearest Earth's pole. In the Northern hemisphere, the connector should be orientated North, in the Southern hemisphere, the connector should be orientated South. If the cable is not oriented to the nearest pole, it does not affect the angle measurement. The angle measurement reflects the tilt and roll of the corresponding sensor position.

<u>For setup at inclined plane</u>: Setup the UV radiometer with signal cable aligned with the installation platform (X', Y'), see figure 5-2B. When the sensor is not aligned, the tilt (X) and roll (Y) measurement does not reflect the angle X' and Y', see figure 5-2C.





Figure 5-2B Tilt and roll angle corresponding to reference plane

Figure 5-2C Tilt and roll angle not corresponding to reference plane

4) Fasten the UV radiometer to the base with the 2 bolts [included] and put the sun screen back on the UV radiometer.

5-3. Wiring

To extend the cable lifetime, make sure that the cables are not exposed to direct sun light or rain/wind by lining the cable through a cable conduit. Cable vibrations will potentially cause noise in the output signal. Fasten the cable so that the cable does not swing or move by wind blowing. Exposure of the signal cable to excessive electromagnetic emissions can cause noise in the output signal as well. Therefore, the cable should be lined at a safe distance from a potential source generating EMC noise, such as an AC power supply, high voltage lines or telecom antenna.

1. Ground connection



The UV radiometer housing is connected to the shield wire of the cable, so connect the shield wire to the ground on the measuring instrument side.

Do not connect the UV radiometer housing to ground. It will be a two-point ground and it cause a noise.



Figure 5-3. MS-10S/11S ground connection method

2. Wiring procedure

Connect the output cable to MS-10S/11S by inserting the cable connector to the receptacle on the body then turn the screw cap. Make sure to check the pin layout of the connector before connecting the cable. If the connector cannot be easily inserted, DO NOT use any force as it will damage the connector. Visually check the pin layout again before retrying to insert the connector. Make sure to fasten the screw cap by turning it all the way.

5-4. Connections

The MS-10S/11S is based on a digital Smart processing interface providing advanced measurement functions with 4 different industrial signal outputs (**Modbus 485 RTU**, configurable **SDI-12**, **4-20mA**, configurable **0-10mA** and **0-1V** with external precision shunt resistor 100Ω).

Table 5-3. UV radiometer outputs

Output	MS-10S/11S
Modbus RTU (Default)	\checkmark
SDI-12	\checkmark
4 - 20 mA (Default)	\checkmark
0 -1V (*)	\checkmark

(*) 0-10mA output with external precision shunt resistor 100Ω

Output parameters	Modbus	SDI-12	4-20mA	0-1V
Irradiance	1	1	1	1
Temperature	1	1		
Tilt position	1	1		
Alerts for abnormal internal humidity of the UV radiometer	1	1		
Sensor information	1	1		

1. Analog output (4-20mA / 0-1V)

MS-10S/11S has two analog outputs (4-20mA and 0-1V). The 4-20mA output is default, the 0-1V(0-10mA) output can be enabled through the "Hibi" software which can be downloaded from the EKO website (MS-10S/11S product page). See appendix 3 to change the current output settings. The current output can be converted into a voltage output when a shunt resistor is used in series. In combination with an external 100 Ω precision resistor (0.1%, 15 ppm) a 0-1V output can be made.

Current output (4-20mA)

Connect the 3 wires with corresponding color to the input terminals of the current meter or data logger (figure 5-4). Connect the power terminals to a DC power supply [8 to 30 V]. We recommend to use a fuse [0.5A] to the DC power supply line [+] for over current protection.



Interconnect the power supply (-) and 4-20mA (-) line. The MS-10S/11S current output requires a 3 wire connection.

- To protect your equipment from noise and surges, the shield wire of the cable must be connected to ground at a single point. If it is not connected, the electronic equipment may be damaged.
- The shield wire of the cable is connected to the surge protection circuit inside the UV radiometer itself and to the enclosure.
- > Be sure to connect a fuse, as this may lead to a fire.



Figure 5-4. How to connect MS-10S/11S (4-20mA output)

Voltage output (0-1V)

The current output can be converted into a voltage output when a shunt resistor is used in series. The default output is 4-20mA. The 0-10mA (0-1V) output is disabled. The settings can be changed when the MS-10S/11S is connected to a PC through the Hibi software, see appendix 3 for instruction.

Connect the 3 wires with corresponding color to the input terminals of the Voltmeter or data logger (figure 5-5). Connect the power terminals to a DC power supply [8 to 30 V]. We recommend to use a fuse [0.5A] to the DC power supply line [+] for over current protection. The precision shunt resistor (0.1%, T.C.R. 15 ppm) need to be placed across the voltage input terminals of the measurement device.



Interconnect the power supply (-) and 0-1V (-) line. The MS-10S/11S voltage output requires a 3 wire connection.

- To protect your equipment from noise and surges, the shield wire of the cable must be connected to ground at a single point. If it is not connected, the electronic equipment may be damaged.
- The shield wire of the cable is connected to the surge protection circuit inside the UV radiometer itself and to the enclosure.
- > Be sure to connect a fuse, as this may lead to a fire.



Figure 5-5. How to connect MS-10S/11S (0-1V output)



When using a shunt resistor to convert current to voltage, use a precision resistor which can make the converted voltage less than two third of the power supply voltage. To convert 0-10mA to 0-1V output, use a 100Ω precision resistor (0.1%, 15ppm). To convert 4-20mA to 1-5V output, use a 250Ω precision resistor (0.1%, 15ppm).

2. Digital output (Modbus / SDI-12)

The MS-10S/11S can work in two digital output modes, respectively Modbus 485 RTU and SDI-12. Modbus 485 output is set to default, the SDI-12 output can be selected through the Hibi software.

PC connection (Modbus)



EKO can provide an optional and approved USB converter for connection with a PC. The converter cable is needed for setup, sensor diagnostics and data logging through the Hibi software. Depending on your region, the optional converter can be different.

- To protect your equipment from noise and surges, the shield wire of the cable must be connected to ground at a single point. If it is not connected, the electronic equipment may be damaged.
- > The shield wire of the cable is connected to the surge protection circuit inside the UV radiometer itself and to the enclosure.
- > Be sure to connect a fuse, as this may lead to a fire.

For any converter with screw terminals or open wires, connect the 4 wires of the sensor cable with the corresponding wire color to the RS-485 to USB converter (figure 5-6). Some converter cables provide a 5V supply voltage from the USB port, in such case no additional power supply is required. In any other case use an additional power supply. Connect the power terminals to a DC power supply [8 to 30 V]. We recommend to use a fuse [0.5A] to the DC power supply line [+] for over current protection.



the power supply and the GND of RS485/USB converter.

Figure 5-6. How to connect MS-11S (Modbus RS485)



Depending on the converter type and design properties, some commercial RS-485 to USB converters may not work properly. A termination resistor is required to prevent reflections from the end of the transmission line. Pull-up and pull-down resistors are necessary to keep the voltage level constant when the transmission line is in a high impedance state.

Connect the 4 wires of the sensor cable with the corresponding wire color to the RS-485 communication port of the data logger master and power supply unit (figure 5-7). Connect the power terminals to a DC power supply [8 to 30 V]. We recommend to use a fuse [0.5A] to the DC power supply line [+] for over current protection.



Figure 5-7. How to connect MS-11S (Modbus RS-485)

MS-10S/11S can be configured within a multi sensor RS-485 Modbus communication network. Up to 31 sensors per one Master can be connected and be assigned with a unique address. For a multiple sensor network the sensors need to be configured according to the recommended RS-485 configuration standards as shown in figure 5-8.

The master represents the data-logging device and slaves represent devices such as MS-10S/11S or other serial devices in the same network. Connect the communication wires of the slave to the modbus communication input of the master. Connect a 120Ω termination resistor at the end of the communication line. The master device may have an integrated termination resistor and pull-up and pull-down resistors. If any communication issues occur, apply those separately.



Figure 5-8. Communication Connection with Modbus RTU



Apply a Termination resistor (typically 120 to 150Ω): Typically reflections occur on long lines, resulting in a receiver misreading logic levels. Proper termination prevents reflections, improving data integrity.
 Apply Pull-up and pull-down resistors (typically 680 to 850Ω): Necessary to keep the voltage level constant when the transmission line is in a high impedance state.



Communication errors may occur depending on the connection distance and the number of connections. In that case, please prepare and apply a RS485 booster or a repeater. Communication problems may occur if Modbus and SDI-12 are used at the same time.



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Although a surge protection board is embedded inside the UV radiometer, if the cable length exceeds 10 m, add an appropriate SPD or the like to protect the measurement system from lightning surges (see A-7).

Data logger connection (SDI-12)

Connect the 3 wires of the sensor cable with the corresponding wire color to the SDI-12 communication port of the data logger master and power supply unit (figure 5-9). Connect the power terminals to a DC power supply [12 V]. We recommend to use a fuse [0.5A] to the DC power supply line [+] for over current protection.



Interconnect the power supply (-) and SDI-12 (-) line.

> Communication problems may occur if Modbus and SDI-12 are used at the same time.



Although a surge protection board is embedded inside the UV radiometer, if the cable length exceeds 10 m, add an appropriate SPD or the like to protect the measurement system from lightning surges (see A-7).



Figure 5-9. How to connect MS-10S/11S (SDI-12)

MS-10S/11S can be configured within a multi sensor SDI-12 communication network. Up to 20 units of Sseries sensors can be connected and be assigned with a unique address(*). For a multiple sensor network the sensors need to be configured according to the recommended SDI-12 configuration standards as shown in figure 5-10. Make sure the cable length between the connecting slave and master be less than 60m. The shield cable must be connected to the ground, otherwise noises may occur.

(*) When connecting other SDI-12 communication devices, the upper limit may change.



Figure 5-10. Communication Connection with SDI-12

3. Overview wire assignments

No.	Wire Color	4-20mA	Modbus	SDI-12	0-1V [*]
1.	Brown (+)	8 to 30VDC (+)	5VDC (+) 8 to 30VDC (+)	12VDC (+)	8 to 30VDC (+)
2.	White (-)	4~20mA (-) / GND	Vcc GND / RS485 GND	Vcc GND	0~10mA (-) / 0-1V (-) / GND
3.	Blue (+)		RS485 (+)	SDI-12 Data (+)	
4.	Black (+)		RS485 (-)		
5.	Gray (+)	4~20mA (+)			0~10mA (+) / 0-1V (+)
Shield	Shield	FG	FG	FG	FG

Table 5-5	Color Code	s of cable	of MS-10S/11S
		3 01 04010	01100-100/110

[*] When selecting 0-1V output, a precision resistor is required separately.



Each number corresponds to the number in Table 5-5.

Figure 5-11. Connector pin number

5-5. Measurements

1. Data logger settings

The output voltage is measured by a measuring device such as a voltmeter or a data logger. If solar irradiance is measured continuously, it is recommended to use a data logger, which has sufficient memory to record data over a longer period and functions to process the measurement parameters of the UV radiometer. Depending on the sensor output which will be used, the data logger should be capable to measure the assigned output type.

For the MS-10S/11S with current output, Modbus 485 RTU and SDI-12, the data logger should have one of those inputs. For MS-10S/11S the input range, resolution and impedance are not critical, and considered as standard for any meteorological or industrial type data logger. For current measurement the measurement range should be selected according to the range settings of the MS-10S/11S.

When configuring the data logger parameters, the sampling rate and data reduction methods can be defined right at the beginning of the data acquisition process. The response time that is given in the specifications of the EKO UV radiometers states the amount of time, which is necessary to reach 95% of the final measurement value. It is also possible to define a 63.2% response [which is equal to 1-1/e]. This time constant, represented by the symbol τ , is 3 times smaller than the values specified by EKO. The recommended ^[1] sampling rate for UV radiometer is smaller than τ . So, for EKO UV radiometers, the sampling rates that have to be programmed in the data logger systems should not exceed the values as given in Table 7-1.

Performing averaging and/or integration of measurement data can be meaningful to, e.g., reduce the data volume or to meet application-specific requirement. Note that shorter sampling rates allow to use shorter averaging/integration times. It could also be meaningful to store not only average values, but to keep track of all statistical values during the averaging period, namely: average, integral, minimum and maximum values, and standard deviation. As a general recommendation, the averaging/integration period should be as short as possible, but long enough to reduce the data volume to store the processed data safely.

Recommendations for irradiance measurements are explained in ^[1] "Guide to Meteorological Instruments and Methods of Observation", WMO reference document No. 8.

2. UV radiometer default settings

The MS-10S/11S is based on a digital Smart processing interface providing advanced measurement functions with 4 different industrial signal outputs (**Modbus 485 RTU**, configurable **SDI-12**, **4-20mA**, configurable **0-10mA** and **0-1V** with external precision shunt resistor 100Ω).

Where to find information regarding the MS-10S/11S defaults settings and important parameters:

Items	Default setting parameters
Sensitivity figure	 Calibration certificate Modbus register SDI-12 register
Modbus 485 RTU (Default)	 Setting report (see appendix A-6 MS-10S/11S setting report) Modbus register Address (last two digits of serial number, 100 if "00") Baud rate 19200 Parity Even
SDI-12	 Setting report SDI-12 register Address 0 Baud rate 1200 Parity Even
4 - 20 mA (Default)	 Setting report 4-20mA = 0 – 150W/m2 or 0 – 10W/m2
0 - 10 mA	 Setting report 0-10mA = 0 – 150W/m2 or 0 – 10W/m2
0 – 1V	 Setting report 0-1V = 0 - 150W/m2 or 0 - 10W/m2

Table 5-6. MS-10S/11S where to find the settings

3. UV Irradiance conversion

4-20mA output

If the measurement range can be selected on the data logger, select the measurement range, which can accurately measure the signal within a range of 4 to 20mA. The output for the MS-10S is set to be 150W/m² at 20mA and MS-11S is set to be 10W/m² at 20mA.

When the UV irradiance current value is \boldsymbol{A} [mA], the UV irradiance \boldsymbol{I} [W/m²] can be determined by the following formula:

MS-10S	<i>I</i> [W/m ²] = (<i>A</i> [mA] - 4) x (150 / 16)
MS-11S	<i>I</i> [W/m²] = (<i>A</i> [mA] - 4) x (10 /16)

0-1V output

If the measurement range can be selected on the data logger, select the measurement range, which can accurately measure the signal within a range of 0 to 1V. The output for the MS-10S is set to be $150W/m^2$ at 1V and MS-11S is set to be $10W/m^2$ at 1V.

When the UV irradiance voltage value is V [V], the UV irradiance I [W/m²] can be determined by the following formula:

MS-10S I [W/m²] = **V** [V] x 150

MS-11S I [W/m²] = **V** [V] x 10

MS-10S/11S [Modbus RTU Output, SDI-12 Output]

When using the digital output (Modbus or SDI-12) by default the irradiance conversion is performed on-board and is one of the measurement parameters within the data string.

4. Daily UV radiant energy

The total daily radiant energy in Joule per meter squared $[J/m^2]$ is obtained by integrating the UV irradiance over time. To calculate the total daily UV radiant energy in Joule per meter square $[J/m^2]$, multiply the averaged UV irradiance *I* [W/m²] by the averaging interval period [s]. Then sum-up the total data number [n] of averaged data points in one day.

Its physical unit is expressed with $[J/m^2]$ and can be calculated with $J = W \cdot S$

$$DTI = \sum_{k=1}^{n} I_{k} \times t^{\mu}$$

6-1. Maintenance

By using the UV radiometers accurate results can be obtained if the glass dome and the condition of the instrument are maintained properly. Furthermore, regular maintenance and scheduled re-calibrations can extend the lifetime of the UV radiometers. However, environmental conditions, such as for instruments mounted near highly frequented traffic lanes or airports, may have a deteriorating effect on the materials. Therefore, proper maintenance is needed and has to be adapted to the local environmental conditions.

The following table describes the common maintenance tasks that should be performed on a regular basis:

Maintenance Item	Frequency How To		Effect
Clean Glass Dome	Several times per week	Keep the glass dome clean by using demineralized water and wiping with a soft cloth dry and clean.	The irradiance measurement will be affected due to a change in transmittance.
Check Appearance Condition	Weekly	Check for cracks and scratches on the glass dome and body.	May lead to shade on the detector and enhanced soiling.
Check Spirit level	Weekly	Verify if the UV-B radiometer is levelled by checking the bubble is in the center ring of spirit level. [When the UV-B radiometer is setup in horizontal position].	An additional cosine/azimuth error will be introduced.
Check Cable Condition	Weekly	Verify if the cable connector is properly connected, tightened to the instrument, and how cable is lined; make sure the cable is not shaking from the wind.	A disconnected cable will cause sporadic reading errors or failure of operation. If the cable is damaged, it may lead to noise or electric shock.
Check Setup Base Condition	Weekly	Check if the instrument is tightened properly to the mounting base plate and the base plate and/or table is securely fastened in a proper condition.	Loose instruments and/or mounting plates can lead to damages of the instruments and/or injury.
Check the Sun screen[*]	Weekly, Before/ After Bad Weather		May lead to damaging the instrument and/or lead to increasing measurement error due to temperature increase by sun screen coming off.
Recalibration	Every 2 Years	To maintain the best possible measurement accuracy, recalibration of the UV-B radiometer is recommended. Contact EKO for more details and requests for a recalibration and maintenance service.	Due to natural aging of materials the detector sensitivity of the UV-B radiometer can gradually change over time.

Table 6-1. Maintenance Items1

Table 6-2. Maintenance Items2 (Advanced remote check can be done)

Maintenance Item	Frequency	How To	Effect
Data validity	Weekly	Check the daytime irradiance data and compare to previous days or adjacent UV-B radiometers.	When large difference occurs operating problems or installation issues can be detected.
Presence of noise	Weekly	Check night-time irradiance values	Night-time offsets and sensor stability issues can be revealed.
Abnormal temperature detection	Weekly	Check the body temperature via Modbus or SDI-12 output.	If the inside temperature becomes abnormally high, the life of the product will be shortened.
Confirm the effect of desiccant	Weekly	Check the relative humidity via Modbus or SDI-12 output.	The condition of the drying agent can slightly change over time. If the relative humidity become high, the glass dome might be fogging up.
Checking the tilt angle	Weekly	Check the tilt angle and roll angle via Modbus or SDI-12 output.	Any change in tilt position after the installation can affect the measurements due to the cosine response of the sensor.

6-2. Troubleshooting

Read the following in case of any sensor trouble. If any questions should remain, please contact EKO for further technical support.

Table 6-3. Troubleshoo Failure	Action
There is no output.	Make sure that the sensor is properly connected, and type of power supply and voltage values are appropriate. Also check the communication settings [i.e. port, baud rate, converter ID] are appropriate.
Output value is too low	The glass dome maybe soiled with rain or dust. Clean the glass dome with demineralized water and soft cloth. The output may decrease over time. Recalibrate periodically.
Negative output signal during night-time.	Since the UV radiometer amplifies a very small signal internally, an offset of several mW/m^2 may occur depending on the installation environment.
Unusual noise	Check the shield connection and make sure it is connected securely. Make sure if the output cable is not shaking from the wind; take necessary measure by fixing or lining the cables through conduit. Check for any objects, which emit electromagnetic wave around the instrument and or cable.
4-20mA and 0-1V output outside range Example) 2mA output when using 4-20mA. The fluctuation of measured current is large.	Check the signal cable connection and make sure it is connected securely. Note that the appropriate ground wire connection method for this product may differ depending on the type of data logger and measurement environment. Select an appropriate ground wire connection method for this product for this product according to the type of data logger and measurement environment.

Table 6-3. Troubleshooting in field

Table 6-4. Troubleshooting Hibi

Failure	Action
No connection with PC	Make sure that the sensor is properly connected, and power supply and voltage levels are appropriate. Also check the communication settings [i.e. port, baud rate, converter ID] are correct.
No communication with USB cable	 If no COM port shows up when Hibi software is started. Reconnect the USB converter and refresh to search new COM devices Check for COM port settings in Windows settings Install an appropriate driver
Settings changes not saved to UV radiometer	Make sure that the sensor is properly connected, and power supply and voltage levels are appropriate. Also check the communication settings [i.e. port, baud rate, converter ID] are correct. Power off/on the UV radiometer, some of the setting are effective after power off/on.

7. Specifications

7-1. Specifications

1. UV-B radiometer Specifications

This product is calibrated to the sunlight spectrum, and is not suitable for measurement of artificial light sources, etc.

Table 7-1	UV radiomete	r specifications
		specifications

Item	MS-10S	MS-11S	
Measurement range	0 to 150 W/m ²	0 to 10 W/m2	
Resolution	0.01 (W/m ²)	0.1 (mW/m2)	
Wavelength range for	245, 400	200.245	
measurement	315-400nm	280-315nm	
Spectral error	< 10%	< 20%	
Non-linearity	<1%		
Temperature response	<±1% (-20 to	o +50℃)	
Cosine response	<±5% (0 t	o 70°)	
Response time	< 0.2	s	
Viewing angle	2π (s	r)	
Operating temperature ^[1]	-40 to +8		
	(Guaranteed accuracy tempera	<u> </u>	
Leveling accuracy	0.1 `		
Inclination sensor accuracy	<±1		
Humidity sensor accuracy	±2%RH (Nom	inal value)	
Temperature sensor	±0.5℃(Maximun	n Tolerance)	
accuracy			
Protection class (IP code)	IP67 equivalent (IEC60529, JIS C0920)		
Weight	0.45kg		
Surface treatment	Anodized aluminum (anodic oxidation treatment)		
	AWG22		
Output cable (O.D.)	0.3mm ² x 5 cores		
Output coble terminal	(φ5.3m Dia terminal	,	
Output cable terminal	Pin terminal 1) Modbus 485 RTU (default	, ,	
	2) SDI-12	,	
Output signal ^[2]	2) SDI-12 3) 4-20mA (default)		
	4) 0-1V (When an external 100Ω precision resistor is used)		
	Operation mode	Voltage Range	
		5Vdc±5% or 8 to 30Vdc±10%	
Supply voltage	SDI-12 :		
		8 to 30Vdc±10%	
		8 to 30Vdc±10%	
	Supply voltage	Recommended load resistance	
Recommended load		100 to 250Ω	
resistance	15 to 24V :	250 to 500Ω	
(4-20mA / 0-10mA)	24 to 30V :	500Ω	
	Operation mode	Power consumption	
Power consumption	Analog output :	< 0.7 W	
	Digital output :	< 0.2 W	

^[1] When the instrument is used in the ambient temperature exceeding the accuracy assurance temperature range, the measurement error may increase.

^[2] Sensor setting can be changed by connecting the sensor to a PC (Use the USB cable (option)) and download the free "Hibi" configurator software from the EKO website.

Table 7-2. Power consumption supply Voltage specific

	5V DC	12V DC	24V DC	Remarks
During	75mW	90mW	110mW	
stand-by	(Approx. 15mA)	(Approx. 7.5mA)	(Approx. 4.5mA)	-
Modbus RS-485	170mW	180mW	190mW	Peak value during
	(Approx. 34mA)	(Approx. 15mA)	(Approx. 8mA)	communication
4-20mA		300mW	640mW	Apply the shunt resistor 250 Ω
output	-	(Approx. 30mA)	(Approx. 27mA)	and 20mA output
0-1V output		300mW	640mW	Apply the shunt resistor 100 Ω
	-	(Approx. 30mA)	(Approx. 27mA)	and 10mA output

7-2. Dimensions

Table 7-3. Dimensions

	MS-10S / MS-11S
A. Fixing Hole Pitch	65 mm
B. Body Height	73 mm
C. Levelling Screw Height	16 mm
D. Width [including Sun screen/Cover]	Ф96 mm
E. Overall Height [approx.]	101mm





Figure 7-1. External Dimensions

7-3. Output Cables

See [5-2. Setup, 2. Wiring] for instruction



Figure 7-2. Output Cables

Different length (10m standard, 20m / 30m / 40m / 50m optional).

2. EKO Converter Cable (Option)



Figure 7-3. EKO Converter cable

7-4. Accessories List

Table 7-4. Accessories List

Option Items	Description	
Output coblo	Cable Length: 10m, 20m, 30m, 50m	
Output cable	Terminals: Fork Terminals, Round Terminals, Pin Terminals	
Ventilation Unit with	MV-01 ventilator and heater	
Heater		
	Converts from RS485 to USB for the communication with MS-10S/11S and allows to	
EKO Converter Cable	connect to PC via USB terminal.	
	Cable Length:5m	

APPENDIX

A-1. Radiometric Terms

Table A-1. Definitions of Terms

Response time	Time required for the output of the ultraviolet radiometer to reach 95%.
Non-linearity	Difference between the output value and the theoretical value for linearly varying light intensity
Directional response	Difference between the output value and the theoretical value for light incident from zenith angles of 0 to 70°.
Spectral error	The maximum spectral mismatch error of the UV radiometer with respect to the spectral irradiance at AM1.5 and AM5 under multiple atmospheric conditions on a clear day, relative to the standard spectral irradiance of AM1.5 as defined in IEC60904-3: 2016 Photovoltaic devices "Measurement principles for terrestrial photovoltaic (PV) solar devices with reference spectral irradiance data".
Temperature response	Output error relative to the output at 20° C when irradiating light at a constant intensity and varying the ambient temperature from -20 to +50°C.

A-2. Software (Hibi)

'Hibi' means 'day by day' in Japanese, and with this software, users will be able to visualize detection signals, set communication parameters, and rapidly troubleshoot any issues from day one. You can change the settings of the MS-10S/11S using this software downloadable from the EKO website (MS-10S/11S product page) and the optional USB cable.

1. Software Installation

Follow the steps below to install "Hibi" configurator software.

- 1) Download the latest version of the "hibi.zip" file [Compressed file: Zip format] from MS-10S/11S product page on the EKO website.
- 2) Unzip "hibi.zip" file and check that the "setup.exe" file exists.
- 3) Run the "setup.exe" file to install "Hibi" configurator software.

2. Hardware Preparation

After the software is installed, connect the MS-10S/11S with the PC to change the setting.

- 1) After installing the software, connect the USB connector of "RS485/USB Converter cable" to the PC.
- Connect the ends of the signal cable of MS-10S/11S to the communication terminal of "RS485/USB converter".
- Connect the power lines of the signal cable to the power supply (DC5V or 8 to 30V), and turn on the power supply. (Refer to Figure A2-1.)



Figure A2-1. Hardware preparation

If you use the optional "EKO Converter cable", you can install it simply by connecting the cable to sensor the main unit. Power for the MS-10S/11S can be supplied via USB. (See Figure A2-2).

* <u>This conversion cable is for installation, so please avoid using it outdoors for a long time. Because the</u> ground wire is not connected, surges can damage your PC during a lightning strike.




3. Software

Start the "Hibi" software and make the required settings.

- 1) Start "Hibi" software. (Launch the software from "EKOApp1.exe" located in the shortcuts or installation folder.)
- 2) After the software starts, the "Welcome" window appears.



Figure A2-3. Welcome window

3) Automatic connection

When using the "Auto-connect" function to connect MS-10S/11S with the "Hibi" software, select the COM port that the RS485/USB converter cable is connected to.



Figure A2-4. Com port select

Click "Select" of "COM port:" on the startup screen, and select the COM port number assigned to the RS485 / USB conversion cable from the displayed COM port numbers.

If you can't find a selectable COM port, click the Refresh button and click Select again to try again.



Figure A2-5. Com port select

Check that the power supply of the main unit is "OFF". Then, click "CONNECT" button.

If the COM port is not recognized, press the refresh button and try again.

Power on the MS-10S/11S within 10 seconds once the "Connecting your sensor" message appears.

When using the "EKO converter cable", connect the cable to the MS-10S/11S within 10 seconds after pressing the "CONNECT" button, and communication will start automatically.



Figure A2-6. Connecting screen

When the connection is completed, the window automatically switches to the "Dashboard" window. In the upper-right corner of the display changes to "UV radiometer Connected".



Figure A2-7. Dashboard

If the connection fails, the screen returns to the "Welcome" screen and "CONNECTION FAILED" is displayed.



Figure A2-8. CONNECTION FAILED

Make sure the connection settings are correct. To perform the "Auto-connection" again, turn off the power of the MS-10S/11S, select "COM port", and then click "CONNECT".

For manual connections, click "View settings" at the bottom of "CONNECTION FAILED" to go to "Settings screen". (As for how to set and connect by "Manual connection", refer to the procedures (4) Manual connection) from the next section.

4) Manual connection

Contact

After turning on the power of the MS-10S/11S, click "CONNECT" without selecting "COM port". Clicking "view settings" at the bottom of the "CONNECTION FAILED" screen moves to the "Settings" screen. (The same screen appears even when the "Auto-connection" fails. To perform manual connection, set and connect using this procedure.)

()

How to auto connect: 1. Select COM port. 2. Power off the sensor. (Don't disconnect the USB cable.) 3. Press CONNECT button. 4. Power on the sensor within 10 seconds.

Connection status Not Connected

۲

on in case.

😐 HIBI 1.1.7.0		-
EKO		Sensor Pyranometer not connected (@
Dashboard	Settings	APPLY CHANGES
🗢 Settings	COMMUNICATION	

COM1

19200

Even

After that, click the "CONNECT" button in Connection status.

Mode Modbus

Auto connect:

COM port:

Baudrate:

Addresses

Parity:

Serial communication

Figure A2-	9 Manua	l connection
i iguic Az-	-9. Manua	

OFF

- C

.

When the connection is completed, "Connected" is displayed.

"XXXX UV radiometer Connected" is also shown in the upper-right corner of the display.

🗢 HIBI 1.1.7.0		– X
EKO		MS-80S Pyranometer connected
- Dashboard	Settings	APPLY CHANGES
🔹 Settings		
	COMMUNICATION	<u>^</u>
	Mode	
	Modbus	O SDI-12 (j)
	Serial communication	Connection status
	Auto connect:	Connected DISCONNECT
	COM port: COM1 COM1	
	Baudrate: 19200 -	
	Parity:	
	Addresses	
Contact	Advantation and discuss for 19876. 1 💌	n v

Figure A2-10. Disconnect appear

When the connection fails, the "Oops..." screen is displayed with the cause of the connection failure.

When connection fail appears

Check that the cable connection, COM port and the communication requirements are correct.

When changing the connection condition after successful connection, set "COM port", "Baud rate" and "Parity" in the "Serial communication" setting of the "COMMUNICATION" items and set "Modbus address [1-247]" and "Register Type" in the "Addresses" setting.

After entering the settings, click "APPLY CHANGES" A confirmation window will be displayed.

Click "YES, SAVE" to make the settings for the MS-10S/11S.

The settings in "Settings" can be saved / read / exported to CSV files.

Click the button with icons in the upper-right corner of "Settings" window.

- "Save" button: Save the settings.
- "Read" button: Read out the settings.
- "Output" button: Output the settings to CSV file



Figure A2-11. Oops screen

0	
You are going to make some important changes that will affect your next measurements.	
Are you sure you want to save the changes?	
NO, CANCEL YES, SAVE	

Figure A2-12. Apply changes screen

• HIBI 1.1.7.0		- ×
EKO		MS-80S Pyranometer connected
Dashboard	Settings	APPLY CHANGES
🗢 Settings		
		"Output" button
	SENSOR INFORMATION	"Read" button
	Ουτρυτ	"Save" button
	TEMPERATURE	~
	SENSOR POSITION	<u> </u>
	DATA FILES	<u> </u>
Contact		

Figure A2-13. Settings screen

5) Setting items

1. COMMUNICATION setting items

Item Name	Setting contents	Setting range
	Modbus	Switch to Modbus 485 RTU interface (Default)
Mode	SDI-12	Switch to SDI-12 interface.
	Auto search	OFF/ON: Manual/Auto-connect
Serial	COM Port	COM1 to COM256
communication	Baud rate	2400 / 4800 / 9600 / 19200 / 38400 / 115200bps
	Parity	Even / Odd / None
	Modbus address	1 to 247 (last 2 digits of serial number is default
	[1-247]	address, 100 when "00")
Addresses	Register Type	S-series/ M-series/ SMP-series/ SRD-series
	SDI-12 address	0 to 9 / A to Z / a to z
Connection status		Connected / Disconnect

😐 HIBI 1.1.7.0					– ×
EKO					MS-80S Pyranometer connected
Dashboard	Settings			8	APPLY CHANGES
🏚 Settings					*
	Mode				
	Modbus			O SDI-12	0
	Serial communi	cation		Connection sta	tus
	Auto connect:	OFF)	 Connected 	DISCONNECT
	COM port:	COM1	C		
	Baudrate:	19200	-		
	Parity:	Even	-		
	Addresses				
	Modbus address [1-247]:	1	_	SDI-12 address:	<u> </u>
	Register Type:	S-series	_		
Contact					3

Figure A2-14. Communication setting screen

Item Name	Setting contents	Setting range	
	Model	Model name registered in the MS-11S (cannot be	
Model		changed)	
information	Serial number	Serial number registered to the MS-11S (cannot be	
		changed)	
	MFG. date	Date of manufacturing (cannot be changed)	
	Firmware version	Firmware version of MS-10S/11S (cannot be changed)	
	Hardware version	Hardware version of MS-10S/11S (cannot be changed)	
	Calibration date	Calibration date and time: Registered at the time of	
Calibration		calibration by the manufacturer, but can also be	
		registered by the user.	
	Sensitivity	Sensitivity constant: Registered at the time of	
	[µV/W/m²]	manufacturer calibration, but can also be registered at	
		the user side.	

2. "SENSOR INFORMATION" setting items

😐 HIBI 1.1.7.0		- ×
EKO		MS-80S Pyranometer connected
🕂 Dashboard	Settings	APPLY CHANGES
🕸 Settings		
	SENSOR INFORMATION	~
	Model information	Calibration
	Model: MS-80S	Calibration date: 01/01/2020 Show detail 🗸
	Serial number: \$1000000	Sensitivity [µV/W/m²]: 10 Show detail V
	MFG. date: 01/01/2020	
	Firmware version: 3.300	
	Hardware version: 7	
	Ουτρυτ	
Contact		

Figure A2-15. Sensor information settings

Item Name	Setting contents	Setting range
	Enable analog	Analog output OFF/ON (selected with the radio
	output	button)
		Either 4-20mA or 0-1V power can be selected.
		* Default is 4-20mA.
	4-20mA	Current(mA)/Irradiance(W/m ²): Setting of minimum
Analog		and maximum irradiance (W/m ²) corresponding to the
output		output.
	0-1V	Voltage(V)/Irradiance(W/m ²): Setting of minimum and
		maximum irradiance (W/m ²) corresponding to the
		output.
	Resistance (ohm)	Load resistor value for calculating output current at 0-
		1V output

3. "OUTPUT" setting items

😑 HIBI 1.1.7.0		- X
EKO		MS-805 Pyranometer connected 💿
Dashboard	Settings	APPLY CHANGES
🗘 Settings	OUTPUT Analog output	^ ×
	Enable analog output: () ou)	O 0-1 V
	Current (mA) Irradiance (W/m²)	Voltage (V) Irradiance (W/m²)
	4 b 0 20 b 1600	0 0 1 1
		Resistance (Ohm): 100
📮 Contact		8

Figure A2-16. Analog settings screen

4. "TEMPERATURE" setting items

Item Name	Setting contents Setting range	
UNIT	Preferred unit	°C -Celsius / °F -Fahrenheit / K-Kelvin
	(temperature unit setting)	

🗢 HIBI 1.1.7.0		– ×
EKO		MS-80S Pyranometer connected
Dashboard	Settings	APPLY CHANGES
🏟 Settings	SENSOR INFORMATION	✓ ■
	OUTPUT	<u> </u>
	TEMPERATURE	<u>^</u>
	UNIT Preferred unit: *C-Cetaius +	
	SENSOR POSITION	~
	DATA FILES	<u> </u>
Contact		

Figure A2-17. Sensor settings screen

The sensor position can be measured in two different planes (X, Y).

<tilt (x="" axis)=""></tilt>	(180° to 0) and (0 to -180°)
<roll (y="" axis)=""></roll>	(180° to 0) and (0 to -180°)

The tilt and roll angles are relative to the calibrated X and Y axis of the sensor and surface mounting plane X' and Y'. When the sensor is positioned in the same plane X = X' and Y = Y', the measured angles X and Y represent the corresponding plane of installation X' and Y'.



Clicking "ZERO ADJUSTMENT" allows you to adjust Tilt (X axis) and Roll (Y axis) of Tilting items using the present tilt angle as 0°. The spirit vial can be used as a reference to readjust the tilt and roll position. For MS-11S X and Y position is factory calibrated.

😐 HIBI 1.1.7.0			– ×
EKO			MS-80S Pyranometer connected
Dashboard	Settings		APPLY CHANGES
🗢 Settings	SENSOR POSITION		<u> </u>
	Position		
	Tilt (X axis) :	0.0 °	
	Roll (Y axis) :	0.0 °	ZERO ADJUSTMENT
	Tilt is defined as the inclination angle with the X axis:	X	Pressing the ZERO ADUSTMENT button will set both values to 0. Please make sure that the spirit vial's bubble on the sensor is perfectly centred.
	Roll is the rotation around the Y axis:		
	DATA FILES		~ 11
🖓 Contact			

Figure A2-18. Sensor Position setting

6. DATA FILES setting items

[Measurements]

<Save file to> Enter the name of the measurement data storage folder.

Default file name format : SensorYYYYMMDDhhmmss.csv

[Sensor settings]

<Save file to> Enter the name of the setting file storage folder.

Default file name format : MS-10S/11S_serialnumber_0_YYYYMMDDhhmmss.ini

•= HIBI 1.1.7.0		- X
EKO		MS-80S Pyranometer connected 💿
- Dashboard	Settings	APPLY CHANGES
🔹 Settings		
	ОИТРИТ	<u> </u>
	TEMPERATURE	<u> </u>
	SENSOR POSITION	<u> </u>
	DATA FILES	<u> </u>
	Measurements 🕡	Sensor settings 🕡
	Save file to: C\EKO_Software\Log\	Save file to: C\EKO_Software\Settings\
Contact		

Figure A2-19. Data Files setting

6) Measurement (Dashboard)

Overview						
Irradiance	Temperature	Humidity	Tilt Angle			
-Ö-	N E		XÂ			
21.5 mW/m ²	23.3 °c	27.2 %	0.0 0.1			

Figure A2-20. Dashboard screen

[Overview]

- Measurement data of irradiance, temperature, humidity, and tilt angle are read from MS-10S/11S every 1 second and displayed.

Irradiance > Irradiance measurement data. Unit: MS-10S is W/m², MS-11S is mW/m².

<Temperature> Internal temperature measurement data.

Unit: selected from °C (Celsius)", "°F (Fahrenheit)" or "K (Kelvin)". (°C: default)

<Humidity> Humidity measurement data (Unit: "%RH")

<Tilt Angle> Tilt (X axis angle) and Roll (Y axis angle) data

[Real-time measurement view]



Figure A2-21. Real-time measurement view

<Real time measurement-Irradiance>

- Display measured irradiance data in a graph (1-second update).
- Drag the graph to change the horizontal axis position and use the mouse wheel to zoom in or out on the desired area.
- The time range of the graph is 00:00:00 to 23:59:59.
- Clicking "Back to default" resets the change of the setting of the graph.

<Data Logging>

Logging function of measurement data

00 0	
"Sample time:"	Set the logging interval for measurement data.
	Setting range: 00:01~01:00 (1 sec to 1 min)
"Average interval:"	Set the logging interval for averaged measurement data.
	Setting range: 00:01~01:00 (1 sec to 1 min)
"Measure intervals:"	Set the time interval for data logging.
	By checking "Continue next days", it is also possible to keep setting
	after the next consecutive days.
	"Start at:" Set the start time for data logging.
	"Ends at:" Set the end time for data logging.
	* Setting across the day is not possible. The start time must be
	earlier than the end time. (Start time < End time)
"LOG DATA buttons:"	Click to start logging measurement data.
	When "STOP" is clicked while measurement data is being logged,
	logging stops.

7) Contact (Contact)

When you click the "Contact" button, the contact page on [EKO Instruments] website appears in the Browser.

es ne Contact EKO Instrumer × + v					- 0	×
← → O ŵ å https://eko-eu.com/contact				☆	LB	
EKO Beyond Accuracy. Products Applicat	ions News About S	Support Contact	EN → eko-eu → ₽			Î
	Conta	act				
	OFFICES REPRE	SENTATIVES				ļ
Get in touch	First name	First name				
Established in 1927, EKO Instruments has now accumulated over 90 years of history and three offices worldwide.	Last name	Last name				
	Company	Company				
000	Address	Address				
	ZIP Code	ZIP Code				
EKO Instruments Co., Ltd.	State	State				Ŷ

Figure A2-22. Contact page @EKO website

8) Sensor internal humidity abnormality alert

Hibi has a sensor internal humidity indication function, which displays an alert when the sensor internal humidity rises and an abnormality is detected. If you see an alert, please contact us.



Figure A2-23. Sensor internal humidity abnormality alert

9) Exiting the software (Hibi)

To exit Hibi, click the "X" in the upper-right corner of the window.

A-3. Communication Specifications (Modbus RTU)

A3-1. Outlines

 \cdot This device is compatible with Modbus RTU*. ASCII modes are not supported.

(* This is an open protocol for serial communication developed by Modicon.)

- The initial setting of the communication interface is Modbus mode. To use the SDI-12 mode, change the settings from "Hibi" software. After changing the setting, turn the power off and then on again to operate with SDI-12. To return to Modbus mode again, change the setting from "Hibi" software.
- · It corresponds to RS485, half-duplex and double-wire multi-drop networks.

The communication specifications are as follows.

Table A3-1. Modbus communication protocol

Optional item	Remarks	
Electrical specifications	EIA-485	
Connection form	Multi-drop method (1 for Master, 31 for Slave, 32 for total)	
Communications protocols	Modbus RTU *1 (Slave)	
Communication speed baud rate	2400, 4800, 9600, 19200, 38400, 115200 bps	
Data length	8 Bit	
Stop bit	1 bit/2 bit *2	
Parity bit	None/Odd/ Even	
Communication distance	Max.1000m (ideal value)	
Error detecting system	CRC-16	

*1: An open protocol developed by Modicon for serial communication.

*2: The value of the stop bit is determined automatically by the parity bit setting.

A3-2. Function code

- \cdot There is no distinction between Coil and Discrete Input addresses.
- \cdot There is no distinction between Holding Register and Input Register addresses.
- \cdot Coil, Discrete Input, Holding Register, Input Register addresses start from "0".

Table A3-2. Supported Function Codes

Function code (hexadecimal)	Function	
0x01	Read Coils	
0x02	Read Discrete Inputs	
0x03	Read Holding Registers	
0x04	Read Input Register	
0x05	Write Single Coil	
0x06	Write Single Register	
0x10	Write Multiple Registers	

A3-3. Communication specification

- \cdot The address range can be used from 1 to 247.
- The maximum frame size that can be communicated at a time is 256 bytes (maximum read registers: 125, maximum write registers: 123).
- \cdot The baud rate (bit/sec) can be selected from 2400, 4800, 9600, 19200, 38400 and 115200.
- · Parity can be selected from "Even", "Odd" or "None".
- · The bit width is 8 bits, the stop bit is 1 bit when parity is present, and 2 bits when parity is absent.
- · If the address and communication settings are changed, the equipment must be restarted.

Setting No.	Bit rate	Parity
0	2400	None
1	2400	Even
2	2400	Odd
3	4800	None
4	4800	Even
5	4800	Odd
6	9600	None
7	9600	Even
8	9600	Odd
9	19200	None
10 (default)	19200	Even
11	19200	Odd
12	38400	None
13	38400	Even
14	38400	Odd
15	115200	None
16	115200	Even
17	115200	Odd

Table A3-3. Communication setting

A3-4. Cable connection

 \cdot RS485 communication ground and the power ground are the same.

Be sure to connect the ground of RS485 communication interface to the power ground.

A3-5. Data format

Table A3-4. Data format to use.

Format	Abstract	
U16	Unsigned 16bit Integer	
S16	Signed 16bit Integer	
U32 Unsigned 32bit Integer		
S32	Signed 32bit Integer	
F32	IEEE754 32bit floating point format	
Str	ASCII characters string	

· The byte order for communication is big endian.

2byte values are sent in the order of H byte \rightarrow L byte

4byte values are sent in the order of H word \rightarrow L word

Character strings are sent in the order of 1 byte from the beginning.

Allocation of each format is shown in the table below.

Table A3-5. Assignment of 8/16/32 bit value

8bit	0x12	0x34	0x56	0x78
16bit	0x1234(MSW)		0x5678(LSW)	
32bit	0x12345678			

Table A3-6. Assignment of 8/16 bits and F32

8bit	0x41	0x45	0x85	0x1E
16bit	0x4145	(MSW)	0x851E(LSW)	
F32		12.3	345	

Table A3-7. Assignment of 8/16bit and Str

81	bit	0x41	0x42	0x43	0x44
16	6bit	0x4142	(MSW)	0x4344	l(LSW)
St	tr		'AB	CD'	

· The 32-bit register is in the order of high word (MSW) followed by low word (LSW).

The following table shows the cases where 0x12345678 is assigned to address n of Modbus register.

Table A3-8. Relationship between 32-bit values and Modbus registers

32-bit value	0x12345678
Modbus register (address n)	0x1234(MSW)
Modbus register (n+1)	0x5678(LSW)

A3-6. Outline of 1 Holding/Input register map

- \cdot The register map starts from address 0.
- · The contents of registers No. 0 to 49 are switched according to the register type setting (No.103).
- · Registers No. 0 to 99 are read-only.
- · Registers after No.100 can be read or written to.

A3-7. No. 0-49 Register details

- The register map changes depending on the register type setting. The following table shows 4 register maps.
- · See in parentheses for the unit.
- · Fixed value if the content is numeric.
- \cdot The blank space is not used. It is filled with zero in U16 format.
- · The abbreviations are as follows.

Addr: Modbus slave address (1-247)

Comp Irr: Irradiance value after compensation of temperature and linearity.

Raw.Irr: Irradiance before correction

- AD: Input voltage
- Sensitivity: Calibration factor
- Cal. Date: Calibration date
- Supply: Supply Voltage
- Sensor Name: Sensor name (MS-11S)
- Firm Ver: Firmware version number
- Hard Ver: Hardware version number
- L. Coeff: Linearity compensation factor, set by No.182-189

0	Model	U16	Model number of the transmitter.		
1	0	U16	Fixed value		
2			Adjusted solar radiation intensity		
3	Comp.Irr	F32	Unit: mW/m ²		
4 to	13 are Reserve				
14	X-axis tilt angle	500	X-axis component of the tilt angle		
15	(degree)	F32	Unit: °		
16	Y-axis tilt angle	500	Y-axis component of the tilt angle		
17	(degree)	F32	Unit: °		
18	-	F32	Intensity of solar radiation before correction		
19	Raw.Irr		Unit: mW/m ²		
20		=	Sensor output voltage		
21	ADmV	F32	Unit: mV		
22			Temperature measured by the internal temperature sensor		
23	Internal temperature	F32	Unit: (°C / °F / K)		
24		500	Relative humidity measured by the internal humidity sensor		
25	Internal humidity	F32	Unit: RH %		
26 to	26 to 49 are Reserve				

Table A3-9. No. 0-49 Register S-series type (default)

Table A3-10. No.0-49 register M-series type

0			Serial No. 1st /2nd ASCII
1			Serial No. 3rd/4th ASCII
2			Serial No. 5th/6th ASCII
3	Serial number	U16	Serial No. 7th/8th ASCII
4	Senarnumber	010	Serial No. 9th/10th ASCII
5			Serial No. 11st/12nd ASCII
6			Serial No. 13rd/14th ASCII
7			Serial No. 15th/16th ASCII
8			"00" (fixed)
9		U16	"00" (fixed)
10	"000000000"		"00" (fixed)
11			"00" (fixed)
12			"00" (fixed)
13	0	U16	Minimum solar radiation intensity 0 (fixed)
14	1600	U16	Maximum solar radiation intensity 1600 (default)
15	2	U16	Measurement Mode (default)
16	Sensitivity	F32	Sensitivity (LSW)
17	(µV/W∙m⁻²)	гэг	Sensitivity (MSW)
18	1	U16	Temperature unit, unit: °C (default)
19	$\Delta D(m)$	E30	Input Voltage (LSW)
20	AD(mV)	F32	Input voltage (MSW)
21	Comp.Irr(mW/m ²)	F32	Corrected insolation intensity (LSW)

22			Corrected insolation intensity (MSW)			
23 t	23 to 24 are Reserve					
25	8355	U16	Password (fixed)			
26 t	o 33 are Reserve					
34		F00	Linearity correction factor 1-k1 (LSW)			
35	L.Coeff. k1	F32	Linearity correction factor 1-k1 (MSW)			
36	L O # 10	F00	Linearity correction factor 2-k2 (LSW)			
37	L.Coeff. k2	F32	Linearity correction factor 2-k2 (MSW)			
38	L O # 10	F32	Linearity correction factor 3-k3 (LSW)			
39	L.Coeff. k3		Linearity correction factor 3-k3 (MSW)			
40	0.0.5	F32	Linearity correction factor 4-k4 (LSW)			
41	L.Coeff. k4		Linearity correction factor 4-k4 (MSW)			
42	Addr	U16	Node number			
43			Communication speed (LSW)			
44	BPS U32	U32	Communication speed (MSW)			
45	Parity	U16	Parity bit			
46 t	46 to 49 are Reserve					

	-				
0	65535	U16	Fixed value		
1	100	U16	Fixed value		
2	1	U16	Fixed value		
3	0	U16	Fixed value		
4	1	S16	Fixed value		
5	Comp.Irr (mW/m ²)	S16			
6	Raw.Irr (mW/m ²)	S16			
7	0	S16	Fixed value		
8					
9	Supply (0.1V)	S16			
10	0	S16	Fixed value		
11	0	S16	Fixed value		
12	0	S16	Fixed value		
13	0	S16	Fixed value		
14	0	S16	Fixed value		
15	0	S16	Fixed value		
16	0	U16	Fixed value		
17	0	U16	Fixed value		
18	AD(0.01uV)	S32			
19					
20	0	S32	Fixed value		
21			Fixed value		
22	0	S32	Fixed value		
23			Fixed value		
24	0	S32	Fixed value		
25			Fixed value		
26	0	U16	Fixed value		
27	0	U16	Fixed value		
28	0	U16	Fixed value		
29	0	U16	Fixed value		
30	0	U16	Fixed value		
31	0	U16	Fixed value		
32	0	U16	Fixed value		
33	0	U16	Fixed value		
34	0	S16	Fixed value		
35 t	o 40 are Reserve				
41	2020	U16	Fixed value		
42	0	U16	Fixed value		
43	Firm Ver	U16			
44	Hard ver.	U16			
45	Address	U16			
46 t	46 to 49 are Reserve				

Table A3-11. No. 0-49 register SMP-series type

able A3-12. No. 0-49 Registers SRD-series type				
0	Address	U16		
1	Com.Set	U16		
2	Comp.Irr(0.01mW/m ²)	000		
3		S32		
4	Raw.Irr(0.01mW/m ²)	S32		
5		332		
6				
7	0	U16	Fixed value	
8	100	U16	Fixed value	
9	100	U16	Fixed value	
10	AD(nV)	S32		
11	AD(IIV)	332		
12 t	o 31 are Reserve			
32				
33				
34		Str		
35	Sensor Name			
36		30		
37				
38				
39				
40	0	U16	Fixed value	
41	Sensitivity	F32		
42	(µV/W∙m⁻²)	гэz		
43	0	U16	Fixed value	
44	0	U16	Fixed value	
45	0	U16	Fixed value	
46	Cal.date	1120		
47	(YYYYMMDD)	U32		
48 t	o 49 are Reserve			

Table A3-12. No. 0-49 Registers SRD-series type

A3-8. Measurement value register update cycle

· The sensor output and the tilt angle measurement value in the register are automatically updated.

The update cycle is about 110 msec. If the data read cycle is less than 110msec, the same data will be read multiple times. The data read cycle should be 110msec or more.

A3-9. Register details from No.50 to 99

- \cdot A fixed value of zero (U16) has been written to an address that is not used.
- \cdot The "EKO" character is written as the company name registration in register No. 96 and 97.

Table A3-13. Register No.50-95

50 to 95 are Reserve

Table A3-14. Register No.96-99

96	Company name (0,1)		The company name in ASCII format "EKO" is read. Four "EKO" characters, three "EKO" characters and one space (0x20).
97	Company name (2,3)	Str	
98	Firmware version	U16	Firmware version number.
99	Hardware version	U16	Various parts of hardware

A3-10. No. 100 or later registers

- · Registers after No.100 are readable and writable, and values written are immediately reflected.
- \cdot To save the written data, use Discrete Coil shown below to save the data.
- The 2 registers, Modbus address (No.101) and serial communication setting (No.102) related to communication are not reflected in the operation after saving and rebooting.

105					
100	Model	U16	Model number of the transmitter. (0x0110)		
101	Modbus Address	U16	Modbus slave address		
100	Serial communication		Set bit rate and parity, see Table A3-3. "Communication		
102	setting	U16	setting"		
			No. Refer to the register type setting Table A3-9 - Table A3-		
103	Register Type	U16	12 of No.0-49 register.		
104 t	to 105 are Reserve		ŬŬ.		
	Setting the analog		Analog current output setting, Table A3-18. "Analog output		
106	outputs	U16	setting details"		
107 t	to 130 are Reserve				
131			Accurate load resistance value, default 100 Ω		
132	0-1V loading resistor	F32	Used to calculate the output current in 0-1V mode.		
	Imediana				
133	Irradiance	F32	Sets the radiance in 0-1V or 0V.		
134	(0-1Vmode 0V)				
135	Irradiance	F32	Sets the radiance in 0-1V or 1V.		
136	(0-1Vmode 1V)	102			
137	Irradiance	500	Radiation intensity value at 4-20 mA mode and output current		
138	(4-20mode 4mA)	F32	of 4mA defaults to 0W/m ²		
139			Radiation intensity value at 4-20mA mode and an output		
	Irradiance	F32	current of 20mA defaults use 150W/m ² (MS-10S) or 10W/m ²		
140	(4-20mode 20mA)		(MS-11S)		
141 to 161 are Reserve					
	162 Date of manufacture				
163		U32	Date of manufacture in YYYYMMDD format		
	Corriging and the set	1100			
164	Serial number	U32			

1654294967295) Enter the number part excluding the alphabet S.166Sensor name (0,1)167Sensor name (2,3)168Sensor name (4,5)169Sensor name (6,7)170Sensor name (6,9)171Sensor name (10,11)172Sensor name (12,13)173Sensor name (14,15)174Tat are Reserve175Sensor name (14,15)176L.Coeff.k1187F32L.Coeff.k2F32188L.Coeff.k3187F32L.Coeff.k4F32188L.Coeff.k4189Cal.Date190Cal.Date191Cal.Value192Cal.Value193Cal.Value194 to 199 are Reserve				Serial number with 32-bit integer value (maximum value		
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $	165			4294967295)		
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $				Enter the number part excluding the alphabet S.		
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $	166	Sensor name (0,1)				
$\begin{array}{c c c c c c c c c c c c c c c c c c c $	167	Sensor name (2,3)				
170Sensor name (8.9)StrNull-terminated unless all 16 characters are used171Sensor name (10,11)Null-terminated unless all 16 characters are used172Sensor name (12,13)Null-terminated unless all 16 characters are used173Sensor name (14,15)Null-terminated unless all 16 characters are used174to 181 are ReserveIterminated unless all 16 characters are used182L.Coeff.k1F32Linear correction factor k1184L.Coeff.k2F32Linear correction factor k2186L.Coeff.k3F32Linear correction factor k3188L.Coeff.k4F32Linear correction factor k4190Cal.DateU32Calibration date in YYYYMMDD format192Cal.ValueF32Calibration value, $\mu V/W \cdot m^{-2}$	168	Sensor name (4,5)				
170Sensor name (8.9)Null-terminated unless all 16 characters are used171Sensor name (10,11)Null-terminated unless all 16 characters are used172Sensor name (12,13) $$	169	Sensor name (6,7)	C tr	Sensor name according to ASCII format, up to 16 characters		
$\begin{array}{c c c c c c c c c c c c c c c c c c c $	170	Sensor name (8,9)	30	Null-terminated unless all 16 characters are used		
173Sensor name (14,15)174 to 181 are Reserve182 183184 184 185L.Coeff.k1F32Linear correction factor k1184 185L.Coeff.k2F32Linear correction factor k2186 187L.Coeff.k3F32Linear correction factor k3188 189L.Coeff.k4F32Linear correction factor k3190 191Cal.DateU32 193Cal.ValueF32Cal.ValueF32Cal.ValueF32Calibration value, μ V/W·m²	171	Sensor name (10,11)				
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $	172	Sensor name (12,13)				
$ \frac{182}{183} + C.Coeff.k1 + F32 + Linear correction factor k1 $ $ \frac{184}{185} + C.Coeff.k2 + F32 + F32 + Linear correction factor k2 $ $ \frac{186}{187} + C.Coeff.k3 + F32 + Linear correction factor k3 $ $ \frac{188}{189} + C.Coeff.k4 + F32 + F32 + Linear correction factor k3 $ $ \frac{188}{189} + C.Coeff.k4 + F32 + Linear correction factor k4 $ $ \frac{190}{191} + C.Coeff.k4 + F32 + Linear correction factor k4 $ $ \frac{190}{191} + C.Coeff.k4 + F32 + Linear correction factor k4 $ $ \frac{190}{191} + C.Coeff.k4 + F32 + Linear correction factor k4 $ $ \frac{191}{191} + C.Coeff.k4 + F32 + Linear correction factor k4 $ $ \frac{192}{193} + C.Coeff.k4 + F32 + Linear correction factor k4 $ $ \frac{192}{193} + C.Coeff.k4 + F32 + Linear correction factor k4 $ $ \frac{192}{193} + C.Coeff.k4 + F32 + Linear correction factor k4 $ $ \frac{192}{193} + C.Coeff.k4 + F32 + Linear correction factor k4 $ $ \frac{192}{193} + C.Coeff.k4 + F32 + Linear correction factor k4 $ $ \frac{192}{193} + C.Coeff.k4 + F32 + Linear correction factor k4 $	173	Sensor name (14,15)				
183L.Coeff.k1F32Linear correction factor k1184 $L.Coeff.k2$ F32 $Linear correction factor k2$ 185 $L.Coeff.k2$ F32 $Linear correction factor k2$ 186 $L.Coeff.k3$ F32 $Linear correction factor k3$ 187 $L.Coeff.k3$ F32 $Linear correction factor k3$ 188 $L.Coeff.k4$ F32 $Linear correction factor k4$ 190 $L.Coeff.k4$ F32 $Linear correction factor k4$ 190 $Cal.Date$ U32Calibration date in YYYYMMDD format192 $Cal.Value$ F32Calibration value, $\mu V/W \cdot m^2$	174 t	o 181 are Reserve				
$\begin{array}{c c c c c c c c c c c c c c c c c c c $	182	L Cooff k1	E30	Linear correction factor k1		
185L.Coeff.k2F32Linear correction factor k2186 $L.Coeff.k3$ F32Linear correction factor k3187L.Coeff.k3F32Linear correction factor k3188 $L.Coeff.k4$ F32Linear correction factor k4189 $L.Coeff.k4$ F32Linear correction factor k4190 $L.Date$ U32Calibration date in YYYYMMDD format192 $L.Value$ F32Calibration value, $\mu V/W \cdot m^{-2}$	183	L.COEII.KT	FJZ			
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $	184	L Cooff k2	E22	Linear correction factor k2		
187L.Coeff.k3F32Linear correction factor k3188 1.000 F32Linear correction factor k4189L.Coeff.k4F32Linear correction factor k4190Cal.DateU32Calibration date in YYYYMMDD format191Cal.ValueF32Calibration value, $\mu V/W \cdot m^{-2}$	185	L.COEII.KZ	гэz			
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $	186		500			
L.Coeff.k4F32Linear correction factor k4190190Cal.DateU32Calibration date in YYYYMMDD format191192Cal.ValueF32Calibration value, μV/W·m²	187	L.COEII.K3	F32	Linear correction factor k3		
189 190 190 Cal.Date 191 U32 192 Cal.Value 193 F32 Calibration value, μV/W·m ⁻²	188		500			
191Cal.DateU32Calibration date in YYYYMMDD format192192Cal.ValueF32Calibration value, μV/W·m²	189	L.Coeff.K4	F32	Linear correction factor k4		
191 192 192 193 Cal.Value F32 Calibration value, μV/W·m ⁻²	190					
193 Cal.Value F32 Calibration value, μV/W·m ⁻²	191	Cal.Date	032	Calibration date in YYYYMMDD format		
193	192		===			
194 to 199 are Reserve	193	Cal.Value F32		Calibration value, µV/W ⋅ m ⁻²		
	194 t	194 to 199 are Reserve				

Table A3-16. Register No.200-219

200 201Cal.Date history0U32Calibration History, Date 0202 203Cal.Value history0F32Calibration History, sensitivity constant 0204 205Cal.Date history1U32Calibration History, Date 1206 207Cal.Value history1F32Calibration History, Date 1208 209Cal.Value history1F32Calibration History, Sensitivity Constant 1208 209Cal.Date history2U32Calibration History, Date 2210 211Cal.Value history2F32Calibration History, Date 2212 213Cal.Date history3F32Calibration History, Sensitivity Constant 2214 215Cal.Date history3F32Calibration History, Date 3214 215Cal.Value history3F32Calibration History, Date 3214 215Cal.Value history3F32Calibration History, Date 3214 215Cal.Value history3F32Calibration History, Date 3215 216 217Cal.Date history4F32Calibration History, Date 4216 217Cal.Date history4F32Calibration History, Date 4				
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	219	Cal.value history4	F32	Calibration History, Sensitivity Constant 4

Table A3-17. Analog output setting details

Analog output setting value	Operation modes
0	Output OFF
1	0-1V Mode
2	4-20 mA Mode

A3-11. Linear correction factor

- \cdot Calculate the UV radiometer output after linear correction using the following equation using the coefficient k1/k2/k3/k4 for the solar radiation meter output V(raw) after temperature correction.
- · Linear post-correction sun photometer output $V(L) = k1 + (k2 \cdot V(raw)) + (k3 \cdot V(raw)^2) + (k4 \cdot V(raw)^3)$
- \cdot The default value is k2=1, k1=k3=k4=0, so V(L)=V(raw), and the raw value is used for the corrected UV radiometer output.

A3-12. UV irradiance after correction

· After the linear correction and temperature correction written above, using the sensitivity value $S(\mu V/W \cdot m^{-1})$

²) for the output voltage, according to the following equation, calculate the irradiance value.

Corrected solar irradiance: $I(C) = V(L) \times 1000/S$

*Since the unit of V(L) is millivolts, multiply it by 1000 to obtain the irradiance value.

A3-13. Outline of Coil / Discrete Input Registers

- \cdot Reboot the device and save the settings by writing a specified bit.
- \cdot Do not write to any Coil other than Reboot/Save.
- · The readout is always zero.

A3-14. Register details

		r	
Addr	Parameter	R/W	Туре
0	-	-	-
1	Reboot	W	Bit
2	-	-	-
3	Save	W	Bit
4	-	-	-
5	-	-	-
6	-	-	_
7	-	-	-

Table A3-18. Coil register

A-4. Communication specification (SDI-12)

A4-1. Abstract

- · SDI-12 (Version:1.4) is supported.
- The initial setting of the communication interface is Modbus. To use the SDI-12 interface, change the settings from "Hibi" software. After changing the setting, turn the power off and then on again to operate with SDI-12 mode. To return to Modbus mode again, change the setting from "Hibi" software.
- When SDI-12 is enabled, the unit operates in "low power standby mode" with power consumption of approx.
 2.5mA (at 12V) during non-communication.

A4-2. Communication specification

 \cdot The communication specifications of SDI-12 are as follows.

Table A4-1. SDI-12 Communication Specifications

Item	Description
Communications protocols	SDI-12 Version 1.4
Baud rate	1,200 bps
Data length	7bit
Stop bit	1
Parity bit	Even
Communication distance	Within 60 m

A4-3. Command list

- \cdot SDI-12 commands are listed below.
- · The lowercase letter 'a' in the command list indicates SDI-12 address number.
- \cdot SDI-12 address number that can be set is 0-9, A-Z, a-z.

Table A4-2. SDI12 Commands

Command	Response	Description
?!	a <cr><lf></lf></cr>	Check the address number of the connected device.
		NOTE: If more than one device is connected, it will not function properly.
		Be sure to use the device alone.
a!	a <cr><lf></lf></cr>	Verify that the device with address number "a" is active.
aAb!	b <cr><lf></lf></cr>	Change the address number of the device with address number "a" to "b".
al!	Refer to the	Returns information.
	right section	<response example=""></response>
		"a14EKOINST_MS-11SV3220000001 <cr><lf>"</lf></cr>
		a: SDI-12 address
		14: SDI-12 version (represents version 1.4)
		EKOInst: Company name (8 characters)
		MS-11S: Sensor model name (6 characters)
		V32: Sensor version (3 characters)
		20000001: Serial number (8 characters)
aM!	a0001 <cr><</cr>	Request the device with address number "a" to execute measurement.
	LF>	0001: indicates the 3-digit measurement execution time (000 indicates

		instantaneous) and the 4th divit indicates the number of data to be
		instantaneous), and the 4th digit indicates the number of data to be
DOL	(000.0.05	returned (1 piece).
aD0!	a+1000.0 <cr< th=""><th>•</th></cr<>	•
aD1! aD2!	> <lf></lf>	The output value is always appended with a sign (+ or -).
aD2! aD3!		If there is more than one output, the sign is also the delimiter.
aD0:		D0: Irradiance (mW/m²) 1 digit after decimal point
		D1: Sensor output voltage (mV) 4 digits after decimal point and Sensor
		temperature (Celsius) 2 digits after decimal point
		D2: X-axis tilt angle (degree) 1 digit after decimal point, forward/backward
		with connector facing back, positive value when back is up, Y-axis tilt
		angle (degree) 1 digit after decimal point, left/right with connector
		facing back, negative value when left is down
		D3: Temperature inside enclosure (°C) 1 digit after the decimal point,
		Humidity inside the enclosure (RH %) 1 digit after the decimal point.
		If the pre-measurement command is "MC", then three CRC characters are
		followed, please refer to SDI-12 standard for the content of CRC
		characters.
aMC!	a0011 <cr><</cr>	Request the device with address number "a" to start measurement and
	LF>	request the CRC to confirm that the command is correctly accepted. The
		response format is the same as "aM!"
aC!	a00101 <cr></cr>	This device is the same as the "aM!" command except for the difference in
	<lf></lf>	the number of response characters.
		The character following a indicates the number of seconds (3 digits) and
		the number of data (2 digits).
aCC!	a00101 <cr></cr>	This transmitter is the same as the "aMC!" command except for the
	<lf></lf>	difference in the number of response characters.
aR0!	a+0.0 <cr><l< th=""><th>Request a measurement from the device with address number "a".</th></l<></cr>	Request a measurement from the device with address number "a".
	F>	Measurement is executed and a response is returned immediately. The
		answer is similar to "aD0!" to" aD2!" command.
aRC0!	a+0.0EmT <c< th=""><th>Request measurement from the device with address number "a" and</th></c<>	Request measurement from the device with address number "a" and
	R> <lf></lf>	request error detection to verify that the command was accepted correctly.
		Measurement is executed and the measured value with three CRC
		characters added at the end is returned instantly.
aXSE!	a+XX.XX <cr< th=""><th>Read the sensitivity constant of this device. Two digits after the decimal</th></cr<>	Read the sensitivity constant of this device. Two digits after the decimal
	> <lf></lf>	point.
aXCD!	aYYYYMMDD	Read the calibration date of this device. YYYY: AD, MM: month, DD: day.
	<cr><lf></lf></cr>	
METADATA	Variable	Identify Measurement Commands and Identify Measurement Parameter
	depending on	Commands are supported.
	request data	

A-5. About recalibration

When recalibrating at a recalibration center other than EKO, the calibration scale of the other center may differ slightly from the UV radiometer calibration scale and sensitivity constants (μ V/Wm⁻²) obtained by EKO. The differences may be caused by differences in the calibration method, differences in the reference standard, measurement uncertainty, and measurement conditions.

If a new sensitivity constant was found and needs to be applied to the UV radiometer, it can be applied in two ways:

 (Post data correction) Multiply the relative difference of the irradiance value measured with the UV radiometer. In this case, the original factory sensitivity value given by EKO remains unchanged. When the new sensitivity figure was found apply the ratio of the new and original calibration figure according to the formula below:

$$I_{new} [W/m^{2}] = \frac{E [\mu V]}{S_{original} [\mu V/W \cdot m^{-2}]} \times \frac{S_{original} [\mu V/W \cdot m^{-2}]}{S_{new} [\mu V/W \cdot m^{-2}]}$$

Example:

It was proven that there was a relative difference in irradiance measured by MS-10S/11S and the reference UV radiometer. In this example the irradiance measured by MS-10S/11S was lower than the irradiance measured by the reference UV radiometer, a new sensitivity value can be calculated and applied by the following equation.

S new	New MS-10S/11S Sensitivity (µV/W/m²)
Sorigin	MS-10S/11S Original Sensitivity (µV/W/m²)
I sensor	Irradiance measured by MS-10S/11S (W/m ²)
I ref	Irradiance measured by reference UV radiometer (W/m ²)

2) (Change the sensitivity figure of the MS-10S/11S) Set a new sensitivity figure to the MS-10S/11S. This can be done via through the Hibi software. Connect the MS-10S/11S to a PC with a RS485/USB converter cable. In settings, the new sensitivity figure can be applied. The original sensitivity figure remains, but will be replaced by the "last" sensitivity figure (µV/W/m²). Multiple calibration figures can be stored inside the UV radiometer, the "last" sensitivity figure is the actual one to calculate the irradiance.

A-6. Setting Report



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S-series Setting Report(Example)

<u>Issue Date</u>:

10-Apr-21

	Factory set	ting data
Sensor type		UV-B radiometer
Model name		MS-11S
Serial number (S*****	* * *)	12345678
Manufacuring date		April 7, 2021
Calibration date		April 5, 2021
Analog sensitivity	[µV/W/m2]	50.12
Hardware version		7
Firmware version (*.***	k)	4000

Current output mode of 4-20 [mA]	Setting
Enable/Disable	Enable (Default)
Output range corresponding to 4-20 [mA].	0 - 10 [W/m2]

Current output mode of 0-10 [mA]	Setting
Enable/Disable	Disable (Default)
Output range corresponding to 0-10 [mA].	0 - 10 [W/m2]

Modbus RTU	Setting
Enable/Disable	Enable (Default)
Address	1
Baudrate	19200
Parity	EVEN
Reg. type	S-series

SDI-12	Setting
Enable/Disable	Disable (Default)
Address	0
Baudrate	1200

A-7. Surge protection

Since a surge protection board is embedded inside the UV radiometer, this alone provides strong protection against lightning surges.

However, if the UV radiometer cable is longer than 10m, or if multiple UV radiometer are connected and the total cable length exceeds 10m, the connected loggers, power supply, and other devices may be damaged by lightning surges.

Please refer to the figure below and add an appropriate SPD to protect the measurement system.

A. Modbus connection (when the cable length exceeds 10m)



Figure A7-1. Modbus connection (when the cable length exceeds 10m, etc.)

*1 *2

If the cable length exceeds 10m, it is recommended to set up an SPD for the communication line and an SPD for the DC power supply because surges may enter from the communication line and the power supply line.

B. SDI-12 connection (when the cable length exceeds 10m)



Figure A7-2. SDI-12 connection (when the cable length exceeds 10m, etc.)

*1 *2

If the cable length exceeds 10m, it is recommended to set up an SPD for the communication line and an SPD for the DC power supply because surges may enter from the communication line and the power supply line.

In the case of lightning surges, the more countermeasure components are used, the lower the probability of failure. However, the type, rating, and connection method of the SPD to be used vary depending on the manufacturer, so please read the instruction manual of each manufacturer carefully.



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